Abstract: The arab writing is originally cursive, difficult to segment and has a great variability. To overcome these problems, we propose two holistic approaches for the recognition of the handwritten arabic words in a limited vocabulary based on the Hidden Markov Models (HMMs): discrete with wk-means and continuous. In the suggested approach, each word of the lexicon is modelled by a discrete or continuous HMM. After a series of pre-processing, the word image is segmented from right to left in succession frames of fixed or variable size in order to generate a sequence vector of statistical and structural parameters which will be submitted to two classifiers to identify the word. To illustrate the efficiency of the proposed systems, significant experiments are carried out on IFN/ENIT benchmark database.

Keywords: Recognition of the handwritten arabic words, holistic approach, DHMMs, CHMMs, k-means, wk-means, algorithm of Viterbi, modified EM algorithm.

1. Introduction

The nature of Arabic script poses some problems in the conventional system of automatic recognition such as words that are not separated along a line, short connection between two successive characters in a word, and the presence of ligatures on the horizontal and vertical strings, which make very difficult the recognition in approaches based on analytical segmentation of characters [27]. A survey and bibliography on recognition of Arabic script covering all the research publications highlighting Arabic text characteristics is presented [2, 8, 27].

Certain research tasks were devoted to the isolated characters [7, 31], others were oriented towards the texts and invested in the segmentation of the words in characters taking into account the aspect related to variation of forms according to their position in the word [37]. Other work were also devoted to the recognition of the isolated handwritten words [4, 6].

According to the manner of perceiving a word, two main methods have been used in the literature, the holistic and analytical approaches. In the first approach, the word is seen as an indivisible entity which preserves the character in its context of vicinity but reduces the recognition vocabulary [6]. The second approach is based on modeling the alphabet of the language and word segmentation entities representing a character or pseudo-character; word recognition is to identify these entities and to propose words hypotheses; this approach is mainly related to the results of segmentation [28] and has the advantage of being able to handle an extended vocabulary.

Most of the works done are focused on combining structural, textual and local features [1, 14, 26], or on introducing a new feature [14]. Recently the problem of writer identification in a multi-script environment [23] and the utility of detecting and removing ruling lines from handwriting documents, for writer identification [15].

The progress made in current years in handwritten Arabic script recognition is due in large part to statistical [23, 34, 36, 37, 47], and structural approaches [3, 5, 45], approaches using neural network [3, 12, 22, 23, 35, 43, 47] approaches based on hidden Markov models [10, 11, 18, 19, 20, 32, 41, 42, 44, 46] and approaches based classifiers combination [9, 23, 41, 47, 48]. Another approach based on Artificial Immune Systems (AIS) and inspired from computer science technique embodies the principles of biological immune-systems for tackling complex real-world problems such as handwritten Arabic script recognition [17].

In order to address the problems associated with the Arabic script processing, some researchers have focused on using a markovian holistic approach for handwriting recognition. This success can be attributed to the probabilistic nature of Hidden Markov Models (HMM) models, which can perform a robust modelling of the handwriting signal with huge variability and sometimes corrupted by noise [21, 30]. Compared to other recognition approaches, HMMs are distinguished by their ability to effectively model various sources of knowledge. Indeed, on one hand they offer a coherent integration of different levels of modeling and on the other hand, the existence of efficient algorithms for
determining the optimum parameters providing the best models, so why HMMs have been used in several works such as those cited in [10, 16, 21, 29].

Motivated by these advantages, our research has been focused on developing recognition systems using Discrete Hidden Markov Models (DHMMs) and Continuous Hidden Markov Models (CHMMs) with global and embedded training, in which we choose an adequate set of statistical and structural features extracted from two types of segmentation, uniform and non-uniform. To evaluate the performance of the suggested approaches tests are carried out on database of Tunisian cities names.

2. Related Works

The very successful use of HMMs in speech recognition has led many researchers to apply them to various problems in the field of handwriting recognition such as character recognition, offline word recognition.

Chen et al. [16] used HMMs with explicit state duration named continuous density variable duration HMM. After explicit segmentation of the word into subcharacters, the observations used are based on geometrical and topological features. Each letter is identified with a state which can account for up to four segments per letter. The parameters of the HMM are estimated using the lexicon and the manually labeled data. A modified Viterbi algorithm is applied to provide the N best paths. Khorsheed [29] has presented a method for offline handwritten script recognition, using a single HMM with structural features. The single HMM is composed by concatenation of multiple character models. After preprocessing, the skeleton graph of the word is decomposed into a sequence of links. The line segment sequence is transformed into discrete symbols by vector quantization. A modified Viterbi algorithm is applied to provide the N best paths. Benouareth et al. [10] describe an extended version of an offline unconstrained Arabic handwritten word recognition system based on segmentation-free approach and discrete HMMs with explicit state duration. After preprocessing intended to simplify the later stages of the recognition process, the word image is first divided according to two different schemes from right to left into frames using a sliding window. Then each frame is represented by a vector having 42 features. This latter sequence is submitted to an HMM classifier to carry out word discrimination by a modified version of the Viterbi algorithm. Several experiments have been performed using the IFN/ENIT benchmark database.

3. Hidden Markov Models

A process of Markov is a system at discrete time being at every moment in a state taken among N distinct states. The transitions between the states occur between two consecutive discrete moments, according to a certain law of probability. An HMM is defined by \( \lambda = (A, B, \pi) \) where A denotes the transition matrix, B the matrix of discrete output probabilities corresponding to each possible discrete observation, and \( \pi \) the initial state distribution [40]. The modeling of real processes by hidden Markov models requires resolution of three problems [9] such as: The assessment of the likelihood of observations sequence \( O=\{o_1, o_2, \ldots, o_T\} \) issued by a model \( \lambda \); the search for the sequence of states \( Q=\{q_1, q_2, \ldots, q_T\} \) of \( \lambda \) that produced the observations; the learning parameters from a model \( \lambda \). In response to the three constraints, most of the researches focus on using simultaneously the Forward-Backward algorithm, the Viterbi algorithm and Baum-Welch algorithm. Discrete HMMs representing a continuous signal into a sequence via discrete vector quantization degrades the performance of the model. It would be advantageous to use hidden Markov models with continuous probability densities.

In the case of continuous HMMs, in addition to the matrix of probabilities of transition and the vectors of initial probabilities, the parameters of the emission probability density of the observations for each state were re-estimated [40].

4. Proposed Systems

The architecture of both developed systems based on DHMM and CHMM are shown respectively in Figures 1 and 2.

![Figure 1. Architecture of discrete hidden markov models.](image-url)
4. Features Extraction

The step of feature extraction consists in extracting the sequence of vectors with structural and statistical features. These features are extracted from right to left, from the picture or the skeleton of the word using the technique of sliding windows with a uniform or non uniform segmentation. In our approach, frame is analyzed and characterized by a vector having 68 features of which 49 are statistical features related to pixels density and 19 structural features that take into account the local configuration, projection points, inflection points, reflection points, diacritical points and loops.

4.3. Statistical Features

a) Histograms of projections and transitions features:

The features of a frame represented by \( F(n, m) \) are computed from histograms of projections and transition. In what follows, \( m \) and \( n \) are the length and width of the frame representing the word.

In the case of histograms of projections and transitions from white to black, for a given frame \( F(n, m) \) four directions have been considered in both cases and they are defined as:

- **Horizontal projection**
  \[ H_{\text{H}}(i) = \sum_{j=1}^{n} F(i, j), \quad 1 \leq i \leq n \]  

- **Vertical projection**
  \[ H_{\text{V}}(j) = \sum_{i=1}^{m} F(i, j), \quad 1 \leq j \leq m \]

- **45° Diagonal projection**
  \[ H_{\text{D}}(k) = \sum_{i=\max(1,k-m),j=\max(1,k-m)}^{\min(n,k),\min(m,k-m)} F(i, j), \quad 1 \leq k \leq m+n-1 \]

- **135° Diagonal projection**
  \[ H_{\text{D}}(k) = \sum_{i=\max(1,k-n),j=\max(1,k-n)}^{\min(n,k),\min(m,k-n)} F(i, j), \quad 1 \leq k \leq m+n-1 \]

- **Horizontal transition**
  \[ HT_{\text{HT}}(i) = \text{NBTNB}(F, i, H), \quad 1 \leq i \leq n \]

- **Vertical transition**
  \[ HT_{\text{VT}}(j) = \text{NBTNB}(F, j, V), \quad 1 \leq j \leq m \]

- **45° Diagonal transition**
  \[ HT_{\text{DT}}(k) = \text{NBTNB}(F, k, D+), \quad 1 \leq k \leq n+m-1 \]

- **135° Diagonal transition**
\[ HT_{NBD,.}(k) = NBTNB \quad (F, k, D,\ldots) \quad (8) \]
\[ 1 \leq k \leq n + m - 1 \]

Where: NBTNB (F, L, D) is a function that evaluates the number of transitions from white to black along a straight line L in the direction D from the frame F.

Based on histograms of projections and transitions, 33 statistical features have been computed from the following equations:

\[ f_1 = \frac{\sum_i H_{p,i}(i)}{n} \quad (9) \]
\[ f_2 = \frac{\sum_i (H_{p,i}(i) - f_1)^2}{n} \quad (10) \]
\[ f_3 = \text{mod} e(H_{p,i}) \quad (11) \]
\[ f_4 = \frac{\sum_i H_{p,i}(j)}{m} \quad (12) \]
\[ f_5 = \frac{\sum_i (H_{p,i}(j) - f_4)^2}{m} \quad (13) \]
\[ f_6 = \text{mod} e(H_{p,i}) \quad (14) \]
\[ f_7 = \frac{\sum_{i=1}^{n-1} H_{p,i}(k) \times L(k)}{n \times m} \quad (15) \]
\[ f_8 = \frac{\sum_{i=1}^{n-1} (H_{p,i}(k) \times L(k) - f_7)^2}{n \times m} \quad (16) \]
\[ f_9 = \text{mod} e(H_{p,i+1}) \quad (17) \]
\[ f_{10} = \frac{\sum_{i=1}^{n-1} H_{p,i}(k) \times L(k)}{n \times m} \quad (18) \]
\[ f_{11} = \frac{\sum_{i=1}^{n-1} (H_{p,i}(k) \times L(k) - f_9)^2}{n \times m} \quad (19) \]
\[ f_{12} = \text{mod} e(H_{p,i+1}) \quad (20) \]
\[ f_{13} = \frac{\sum_i HT_{NBD,.}(k)}{n} \quad (21) \]
\[ f_{14} = \frac{\sum_i (HT_{NBD,.}(k) - f_{13})^2}{n} \quad (22) \]
\[ f_{15} = \text{mod} e(H_{NBD,.}) \quad (23) \]
\[ f_{16} = \min(HT_{NBD,.}) \quad (24) \]
\[ f_{17} = \max(HT_{NBD,.}) \quad (25) \]
\[ f_{18} = \frac{\sum_i HT_{NBD,.}(j)}{m} \quad (26) \]
\[ f_{19} = \frac{\sum_i (HT_{NBD,.}(j) - f_{18})^2}{m} \quad (27) \]
\[ f_{20} = \text{mod} e(H_{NBD,.}) \quad (28) \]
\[ f_{21} = \min(HT_{NBD,.}) \quad (29) \]

\[ f_{22} = \max(HT_{NBD,.}) \quad (30) \]
\[ f_{23} = \frac{\sum_{i=1}^{n-1} HT_{NBD,.}(k) \times L(k)}{n \times m} \quad (31) \]
\[ f_{24} = \frac{\sum_{i=1}^{n-1} (HT_{NBD,.}(k) \times L(k) - f_{22})^2}{n \times m} \quad (32) \]
\[ f_{25} = \text{mod} e(H_{NBD,.}) \quad (33) \]
\[ f_{26} = \min(HT_{NBD,.}) \quad (34) \]
\[ f_{27} = \max(HT_{NBD,.}) \quad (35) \]
\[ f_{28} = \frac{\sum_{i=1}^{n-1} (HT_{NBD,.}(k) \times L(k) - f_{23})^2}{n \times m} \quad (36) \]
\[ f_{29} = \text{mod} e(H_{NBD,.}) \quad (37) \]
\[ f_{30} = \min(HT_{NBD,.}) \quad (38) \]
\[ f_{31} = \max(HT_{NBD,.}) \quad (39) \]
\[ f_{32} = \max(HT_{NBD,.}) \quad (40) \]
\[ f_{33} = \frac{m}{n} \quad (41) \]

b) Density features:

Let \( U \) and \( L \) respectively the upper and lower values of the baseline. \( H \) represents the height in pixels of the sliding window (height of the bounding box of the word processed). The window is divided vertically into \( nC \) cells, that is \( n(i) \) the number of pixels of writing (black pixels) in the cell \( i \).

Let \( b(i) \) the intensity of the cell \( i: b(i)=0 \) if \( n(i)=0, b(i)=1 \) otherwise. The characteristics of density are:

\[ f_{34}: \text{density of black pixels in the window.} \]
\[ f_{35}: \text{number of transitions from black to white between cells.} \]
\[ f_{36}: \text{difference in position between the centers of gravity} \]
\[ \text{of writing pixels in two consecutive windows:} \]
\[ f_{37} \text{ to } f_{44}: \text{the densities of pixels in each writing column of the window.} \]

The following features depend on the estimated position of the baseline.

\[ f_{45}: \text{normalized vertical gravity center of the writing} \]
\[ \text{pixels compared to the low baseline.} \]
\[ f_{46} \text{ to } f_{47}: \text{writing pixel densities above and below the low} \]
\[ \text{baseline.} \]
\[ f_{48}: \text{number of transitions from black to white between cells located above the low} \]
\[ \text{baseline.} \]
f₄₀: zone belongs to the gravity center of writing in the window, it could be upper (f₄₀=1), middle (f₄₀=2) or lower (f₄₀=3).

4.3.2. Structural Features

a) Local configurations features:

Concavity features are features that provide local concavity information and stroke direction within each frame. Each concavity feature f₅₀ to f₅₄ represents the (normalized) number of white pixels (background) that belong to five types of concavity configurations. They are explored by using a 3 x 3 window, as shown in Figure 5.

![Figure 5. The five local configurations around a background pixel P](image)

The following characteristics f₅₅ to f₅₉ depend on the positions of the baselines and the number of pixels located in the middle of writing between the two baselines.

b) Projecting points:

They correspond to points in the word skeleton with a number of neighbors different to 0 and 2. There are two types: the extreme points and junction points. An extreme point correspond the start / end of a line segment. A junction point connects three branches or more. For the latter, there are two types: the branch points and crossing points. f₆₀=E, f₆₁=B and f₆₂=C.

Where E, B and C are respectively the number of extremes points, branch points and crossing points in the frame F.

c) Inflection points

They correspond to the sign changes of the curvature. f₆₃=I.

Where I is the number of inflection points in the frame F.

d) Reflection points

They correspond to the skeleton points Pᵢ for which the sum of the smoothed curves of the previous sequence of points Pᵢ is positive (respectively negative). The overall smoothed curvature is defined by:

\[ \delta_{\alpha} = \theta_{(i+1,j)} - \theta_{(i,j)} \] (45)

With

\[ \theta_{\alpha} = \arctg \left( \frac{y_i - y_{i-1}}{x_i - x_{i-1}} \right) \] (46)

Where (xᵢ, yᵢ) are the coordinates of point P on the curve analysis (i.e., sequence of points in the skeleton), and S is a smoothing factor, in other words, the optimal interval for which the noise quantization is reduced and significant details are preserved in each point of the curve. For a smooth curve, the value of S must experimentally be in the range (5 to 15). The optimal value for S was empirically fixed at 7. f₆₄=R.

Where R is the number of reflection points in the frame F.

e) Diacritical points

These are the black pixels in the skeleton with a number of neighbors equal to 0. This type of points characterizes the formed characters of the secondary parts. These are distinguished by their positions relative to baseline (below or above). f₆₅=DB, f₆₆=DH.

Where DB and DH are the number of diacritic points being below or above the baseline in the frame F.

f) Loops

They correspond to the internal contours of the word image, and can be easily calculated from the skeleton of the word. The loops are distinguished by their degree of inclusion (integral or partial) in the frame in question. f₆₇=BP, f₆₈=BI.

Where BP and BI are the number of loops partially and completely included in the frame F.

4.4. Learning

The topology adopted for the global modeling of handwritten Arabic words is that of right-left with break inter-state and intra-states [40]. This type of model has the advantage of roughly keeping the notion of time in the modeling, thus approaching the nature of writing. However, we must define the different parameters in the model structure (“Number of states, N”, “transition class”, “Number of Gaussian, G”). The choices about the exact structure of the model can be identified fairly empirical and are still not easily justifiable. In our case, the values of numbers of states and Gaussians were empirically determined, those which give the best recognition rate. For learning, the algorithm of Baum-Welch based on a criterion of maximum likelihood is used for the optimization of HMMs parameters.

4.4.1. Vectors Quantization and Discrete HMMs Modeling

In the modeling of discrete HMMs, the words and their probability densities observations are discrete and require the use of a vector quantizer to match continuous vector to a discrete index of a dictionary of reference (CodeBook). Once the dictionary reference
is obtained, the correspondence between the characteristic vectors of the frames and the indices of the dictionary is evaluated by the method of the nearest neighbor.

This procedure is achieved through three steps: the partition of the characteristic vectors obtained from all learning images in disjoined units; the representation of each set by a single vector \( v_k = 1 \leq k \leq M \), which is usually the centroïde vector of characteristics of the training set assigned to the same class and the optimization of the partition of the dictionary (the centroïde of each region). In our case, hybridizes Invasive Weed Optimization with K -means have been used; the solutions generated by the Invasive Weed Optimization Algorithm are used as initial solutions for the K-means algorithm [13].

Two types of modeling were implemented in the case of DHMM:

- **The holistic learning**: The concept of state is associated to the number of character in the word. Consequently, the number of HMM states varies from one model to another. For example, the model associated with the word “ما رة” contains 4 states, whereas the number of states in the model of “القيروان” is 8 states.

- **Embedded learning**: Each character is modeled by an HMM model, thus the modeling of the word is carried out by the concatenation of the models characters, the number of states of characters is evaluated experimentally.

### 4.4.2. Continuous Hidden Markov Model

The choice of the number of Gaussian mixtures and the number of states is crucial in designing an appropriate model. In practice, the number of states and Gaussian model in learning process are fixed, where each frame may belong to any state with some probability.

### 4.4.3. Recognition

The classification of the word is based on a modified EM algorithm for mixture models based on the Bregman divergence [24]. For each model \( \lambda \), the word \( v \) of lexicon \( L \), the classifier computes the probability \( p(O|\lambda_v) \) which corresponds to the probability of obtaining the sequence \( O \) of model \( \lambda_v \).

### 5. Results and Discussions

To validate the suggested approach, significant experiments have been performed on the IFN/ENIT benchmark database composed of 26459 Arab words corresponding to a lexicon of 946 of Tunisian cities names written by 411 scriptwriters. This database is composed of four distinct units (a, b, c, d) among which three are used for training and one for testing. Several tests were carried out to evaluate the rate of recognition of the two systems, according to modeling types, number of states (N), size of quantization codebook (M), procedure of segmentation word image and the number of Gaussian (G).

Experimentally we define the values of parameters which give the best rate recognition. Tables 1 and 2 shows respectively the values of the parameters and the configuration of the database for learning and testing.

<table>
<thead>
<tr>
<th>Number of gaussiennes (G)</th>
<th>DHMMs</th>
<th>CHMMs</th>
<th>Embedded learning</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td>25</td>
<td>X</td>
<td>25</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Number of states (N)</th>
<th>Define</th>
<th>Define</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>4</td>
<td>4</td>
</tr>
</tbody>
</table>

**Table 1.** DHMMs/CHMMs parameters and configurations.

<table>
<thead>
<tr>
<th>Number of states (N)</th>
<th>Data</th>
<th>Size</th>
<th>Data</th>
<th>Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>a, b, c</td>
<td>20209</td>
<td>D</td>
<td>6250</td>
</tr>
<tr>
<td>2</td>
<td>a, c, d</td>
<td>20010</td>
<td>B</td>
<td>6449</td>
</tr>
<tr>
<td>3</td>
<td>b, c, d</td>
<td>19069</td>
<td>A</td>
<td>7390</td>
</tr>
<tr>
<td>4</td>
<td>a, d</td>
<td>20089</td>
<td>C</td>
<td>6370</td>
</tr>
</tbody>
</table>

**Table 2.** Configurations used for learning and test.

The non uniform segmentation of handwritten Arabic words in a series of frames seems better suited to modeling based on CHMMs. Tables 3 and 4 shows that the average gain rate obtained in top 10 is 1,27% for embedded learning and 1,81 % for holistic learning. Indeed, this segmentation method has the advantage in giving in most cases, the frame that has the form of complete characters or parts of characters.

On the other hand, the uniform segmentation process often generates frames whose form is a combination of characters which will lead to the recognition phase, the risk of confusion at character level allowed the choice to emit this frame.

<table>
<thead>
<tr>
<th>Test</th>
<th>Segmentation</th>
<th>Top1</th>
<th>Top2</th>
<th>Top6</th>
<th>Top10</th>
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<tbody>
<tr>
<td>1</td>
<td>Uniform</td>
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<td>85,45</td>
<td>90,75</td>
<td>91,95</td>
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<td>Non uniform</td>
<td>82,79</td>
<td>86,66</td>
<td>91,83</td>
<td>92,89</td>
</tr>
<tr>
<td>2</td>
<td>Uniform</td>
<td>80,54</td>
<td>83,79</td>
<td>88,93</td>
<td>90,50</td>
</tr>
<tr>
<td></td>
<td>Non uniform</td>
<td>81,62</td>
<td>85,15</td>
<td>90,33</td>
<td>91,80</td>
</tr>
<tr>
<td>3</td>
<td>Uniform</td>
<td>79,42</td>
<td>81,25</td>
<td>86,15</td>
<td>88,61</td>
</tr>
<tr>
<td></td>
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<td>80,74</td>
<td>83,75</td>
<td>88,46</td>
<td>90,63</td>
</tr>
<tr>
<td>4</td>
<td>Uniform</td>
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<td>87,88</td>
<td>90,96</td>
<td>92,94</td>
</tr>
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<td>Non uniform</td>
<td>84,46</td>
<td>88,62</td>
<td>91,66</td>
<td>93,75</td>
</tr>
</tbody>
</table>

**Table 3.** Recognition rates obtained with discrete HMMs modelling and embedded learning.

<table>
<thead>
<tr>
<th>Test</th>
<th>Segmentation</th>
<th>Top1</th>
<th>Top2</th>
<th>Top6</th>
<th>Top10</th>
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</thead>
<tbody>
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<td>1</td>
<td>Uniform</td>
<td>41,69</td>
<td>49,20</td>
<td>51,79</td>
<td>52,92</td>
</tr>
<tr>
<td></td>
<td>Non uniform</td>
<td>50,95</td>
<td>52,06</td>
<td>53,59</td>
<td>54,97</td>
</tr>
<tr>
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<td>Uniform</td>
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<td>48,13</td>
<td>50,91</td>
<td>51,68</td>
</tr>
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<td>Non uniform</td>
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<td>50,24</td>
<td>51,35</td>
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<td>47,56</td>
<td>49,72</td>
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<td></td>
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<td>49,63</td>
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<td></td>
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<td>51,84</td>
<td>53,19</td>
<td>54,24</td>
<td>56,66</td>
</tr>
</tbody>
</table>

**Table 4.** Recognition rates obtained with discrete HMMs modelling and holistic learning.
The non uniform segmentation of handwritten Arabic words in a series of frames seems better suited to modeling based on continuous HMMs. Average gain rate is obtained in top 10 is 1.01% for embedded learning and 1.88% for holistic learning as shown in Table 5 and 6. In all performed tests, the best recognition rate is obtained experimentally by continuous Markovian modeling for 4 states with 25 Gaussian mixtures and non uniform segmentation.

Table 5. Recognition rates obtained with continuous HMMs modeling and embedded learning.

<table>
<thead>
<tr>
<th>Test</th>
<th>Segmentation</th>
<th>Top1</th>
<th>Top2</th>
<th>Top6</th>
<th>Top10</th>
</tr>
</thead>
<tbody>
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<td>1</td>
<td>Uniform</td>
<td>84.66</td>
<td>87.88</td>
<td>92.90</td>
<td>95.58</td>
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<td>Non uniform</td>
<td>85.37</td>
<td>89.18</td>
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</tr>
<tr>
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<td>Uniform</td>
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</tr>
<tr>
<td></td>
<td>Non uniform</td>
<td>86.88</td>
<td>90.75</td>
<td>95.93</td>
<td>97.44</td>
</tr>
<tr>
<td>3</td>
<td>Uniform</td>
<td>83.25</td>
<td>86.55</td>
<td>90.19</td>
<td>93.66</td>
</tr>
<tr>
<td></td>
<td>Non uniform</td>
<td>84.42</td>
<td>87.88</td>
<td>92.75</td>
<td>94.32</td>
</tr>
<tr>
<td>4</td>
<td>Uniform</td>
<td>86.65</td>
<td>91.94</td>
<td>94.56</td>
<td>98.36</td>
</tr>
<tr>
<td></td>
<td>Non uniform</td>
<td>89.29</td>
<td>92.77</td>
<td>95.86</td>
<td>99.66</td>
</tr>
</tbody>
</table>

Table 6. Recognition rates obtained with continuous HMMs modelling and holistic learning.

<table>
<thead>
<tr>
<th>Test</th>
<th>Segmentation</th>
<th>Top1</th>
<th>Top2</th>
<th>Top6</th>
<th>Top10</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Uniform</td>
<td>48.75</td>
<td>50.25</td>
<td>52.78</td>
<td>53.66</td>
</tr>
<tr>
<td></td>
<td>Non uniform</td>
<td>51.55</td>
<td>53.44</td>
<td>54.30</td>
<td>55.19</td>
</tr>
<tr>
<td>2</td>
<td>Uniform</td>
<td>49.72</td>
<td>51.14</td>
<td>53.06</td>
<td>54.85</td>
</tr>
<tr>
<td></td>
<td>Non uniform</td>
<td>52.58</td>
<td>54.36</td>
<td>55.79</td>
<td>56.65</td>
</tr>
<tr>
<td>3</td>
<td>Uniform</td>
<td>46.85</td>
<td>48.68</td>
<td>50.55</td>
<td>51.79</td>
</tr>
<tr>
<td></td>
<td>Non uniform</td>
<td>49.42</td>
<td>51.21</td>
<td>52.44</td>
<td>53.88</td>
</tr>
<tr>
<td>4</td>
<td>Uniform</td>
<td>51.35</td>
<td>53.18</td>
<td>55.89</td>
<td>56.76</td>
</tr>
<tr>
<td></td>
<td>Non uniform</td>
<td>53.24</td>
<td>55.41</td>
<td>56.65</td>
<td>58.87</td>
</tr>
</tbody>
</table>

Also note that in the non uniform segmentation, the average gain rate obtained with continuous HMM in top 10 is 4.79% for embedded learning and 1.78% for holistic learning compared to discrete HMM.

A comparison made between the proposed system (CHMMs) and others systems such as UOB [19], SCHMMs with explicit state duration [10], TH-OCR, REAM and ARAB-IFN shows that continuous HMMs provides better results with proposed set of features as shown in Table 7.

Table 7. Comparison with others systems which are represented in [10, 19, 33] : with the dataset d (6735 images).

<table>
<thead>
<tr>
<th>Systems</th>
<th>Features</th>
<th>Top1</th>
<th>Top6</th>
<th>Top10</th>
</tr>
</thead>
<tbody>
<tr>
<td>UOB</td>
<td>49 statistical</td>
<td>85.00%</td>
<td>93.56%</td>
<td></td>
</tr>
<tr>
<td>SCHMms with explicit</td>
<td>3 statistical + 9 structural</td>
<td>89.08%</td>
<td>95.98%</td>
<td></td>
</tr>
<tr>
<td>state duration</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TH-OCR</td>
<td>structural</td>
<td>30.13%</td>
<td>46.59%</td>
<td></td>
</tr>
<tr>
<td>REAM</td>
<td>Structural</td>
<td>89.06%</td>
<td>99.62%</td>
<td></td>
</tr>
<tr>
<td>ARAB-IFN</td>
<td>Statistical</td>
<td>87.94%</td>
<td>95.62%</td>
<td></td>
</tr>
<tr>
<td>Proposed DHMMs</td>
<td>49 statistical + 19 structural</td>
<td>84.46%</td>
<td>93.75%</td>
<td></td>
</tr>
<tr>
<td>Proposed CHMMs</td>
<td>49 statistical + 19 structural</td>
<td>89.29%</td>
<td>99.66%</td>
<td></td>
</tr>
</tbody>
</table>

The system is trained on a reduced set with 1000 names.

6. Conclusions

In this paper, we have proposed a modeling approach based on hidden Markov models, discrete and continuous. Many improvements have been planned such as: the learning strategy, the algorithm display, the selection and extraction of features from the word image. We have adopted two methods for segmenting the word into a sequence of frames namely uniform and non uniform segmentation. On the other hand, the nonuniform segmentation scheme is more appropriate than the uniform one.

We have studied the influence of different parameters that are involved in the construction of a Markov model such as the number of states and the number of Gaussians. Frame is analyzed and characterized by a vector having 68 components and combining a new set of relevant statistical related to pixels density and structural features that take into account the local configuration, projection points, inflection points, reflection points, diacritical points and loops. The performances of recognition obtained by our approach are acceptable; they have shown that modeling word recognition using hidden Markov models with continuous probability density improves the discriminating power and speeds up the computation time. The rates of goodness recognition using continuous hidden Markov model with non uniform segmentation and embedded learning are higher than those obtained by discrete HMMs; this improvement varies from 2.52% to 5.91%.

In addition, the recognition rates obtained by our system based CHMMs are greater than those obtained by UOB, SCHMMs with explicit state duration, DHMMs, TH-OCR, REAM and ARAB-IFN. The experiments show that significant improvements can be achieved by using a strategy that reinforces the classifier performances by using an adequate mechanism of selecting the parameters or attributes which are most relevant to an appropriate approach.

Acknowledgments

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